

b)	A Lossy cable which has $R = 25.23 \Omega/m$, $L = 26H/m$, $C = 2pF/m$, and $G = 0$ operates at $f = 5MHz$. Find the attenuation constant and phase constant of the line.	L3	CO4	5 M
OR				
11 a)	Discuss the condition for lossless transmission lines.	L2	CO4	5 M
b)	Derive the transmission line equations.	L3	CO4	5 M

Code: 23EC3401

II B.Tech - II Semester – Regular Examinations - MAY 2025**ELECTROMAGNETIC WAVES AND TRANSMISSION LINES****(ELECTRONICS & COMMUNICATION ENGINEERING)**

Duration: 3 hours

Max. Marks: 70

- Note: 1. This question paper contains two Parts A and B.
 2. Part-A contains 10 short answer questions. Each Question carries 2 Marks.
 3. Part-B contains 5 essay questions with an internal choice from each unit. Each Question carries 10 marks.
 4. All parts of Question paper must be answered in one place.

BL – Blooms Level

CO – Course Outcome

PART – A

		BL	CO
1.a)	Define distance vector with an example.	L2	CO1
b)	Write a short notes on continuity equation.	L2	CO1
c)	Write any two Maxwell's equations in point form.	L2	CO2
d)	Define Magnetic Flux Density.	L2	CO2
e)	Distinguish conduction and displacement current densities.	L2	CO3
f)	Define Faraday's law.	L2	CO3
g)	Give the expressions for Wave equations.	L2	CO3
h)	Define skin depth.	L2	CO3
i)	A $100+j50\Omega$ load is connected to a 75Ω lossless line. Find Γ .	L2	CO4
j)	Write the relation between VSWR and Reflection Coefficient.	L2	CO4

PART – B

			BL	CO	Max. Marks
UNIT-I					
OR					
2	a)	With neat diagram, Explain the spherical system with coordinates (r, Θ, ϕ) .	L2	CO1	5 M
	b)	A uniform line charge $\rho_L = 25\text{nC/m}$ lies on the axis $x=3\text{m}$ and $y=4\text{m}$ in free space. Calculate the electric field intensity at a point $(2,3,15)\text{m}$.	L3	CO2	5 M
UNIT-II					
3	a)	Define Gauss's Law? Derive an equation $\nabla \cdot D = \rho_v$.	L3	CO1, CO2	5 M
	b)	Derive Laplace's and Poisson equation.	L3	CO2	5 M
OR					
4	a)	Define and Explain Ampere's circuit law.	L2	CO2	5 M
	b)	Determine J at $(2,0,0)$ in cylindrical coordinates if the magnetic field, $H = 50 \sin\phi a_z \text{ mA/m}^2$.	L3	CO2	5 M
OR					
5	a)	In a magnetic field, $H = 2a_x + 5a_y + 1a_z \text{ A/m}$ exists at a point in a medium $\mu_r = 4$. Calculate the magnetic flux density at the point.	L3	CO2	5 M
	b)	State Biot-savart law and obtain the expression for magnetic field intensity at a point P due to an infinite current line element.	L3	CO2	5 M

UNIT-III					
6		With necessary explanation, derive the Maxwell's equation in differential and integral forms for time varying fields.	L3	CO3	10 M
OR					
UNIT-IV					
7	a)	Given the conduction current density in a lossy dielectric as $J_c = 0.02 \sin 10^9 t \text{ A/m}^2$. Calculate the displacement current density if $\sigma = 103 \text{ mho/m}$ and $\epsilon_r = 6.5$.	L3	CO3	5 M
	b)	What is inconsistency in Ampere's law? Develop an expression for the displacement current density.	L3	CO3	5 M
OR					
8		Define the terms Good conductor and loss less Dielectrics. Discuss about Wave propagation Characteristics in Good conductors.	L2	CO3	10 M
	a)	State and prove Poynting theorem.	L2	CO3	5 M
	b)	Explain about Circular and Elliptical polarization.	L2	CO3	5 M
UNIT-V					
10	a)	Derive an equation of two-wire transmission line Input Impedance.	L3	CO4	5 M

II B.Tech-II Sem - Regular Examinations - May 2025
 Electromagnetic Waves and Transmission Lines

ECE

Scheme of valuation

Part A

1. a) Definition (or) formula - 1M } 2M
 Example - 1M }
 - b) formula - 1M } - 2M
 Explanation - 1M }
 - c) Any two Maxwell's equations - 2M
 - d) Definition - 2M
 - e) Any two differences - 2M
 - f) Definition - 2M
 - g) Two Equations - 2M
 - h) Formula (or) Definition - 2M
 - i) Formula - 1M } 2M
 Answer - 1M }
 - j) Formula - 2M
- 2a) Diagram - 2M } 5M
 Explanation - 3M }
- 2b) Formula - 2M } 5M
 Substitution - 2M }
 Answer - 1M }
- 3a) Definition - 2M } 5M
 Derivation - 3M }

3b) Necessary equations - 2M } 5M
Derivation - 3M

4a) Definition - 2M } 5M
Explanation - 3M

4b) Formula - 2M
Substitution & Simplification 2M } 5M
Answer - 1M

5a) Formula - 2M
Substitution & Simplification 2M } 5M
Answer - 1M

5b) Statement - 2M } 5M
Derivation - 3M

6a) Maxwell's equation 4M }
Derivation & explanation 6M } 10M

7a) Formulas - 2M
Substitution & Simplification 2M } 5M
Answer - 1M

7b) Necessary equation - 2M } 5M
Derivation - 3M

8) Definitions - 4M } 10M
Explanation - 6M

9a) Statement - 2M } 5M
Proof - 3M

9b) Each type - 2.5M total 5M

10a) Derivation - 5M

10b) Formulas - 2M } 5M
Substitution & Answer - 3M

11a) Derivation & Explanation - 5M

11b) Minimum - 2M into derivative form 2M, final form - 1M

II B.Tech - II Semester - Regular Examinations May - 2025

Electromagnetic Waves and Transmission Lines

Dept. of ECE

Scheme of Valuation

1. a) The distance vector in the displacement from one point to another.

$$\text{Ex:- } \mathbf{A} = a\mathbf{x} + 3a\mathbf{z} \text{ and } \mathbf{B} = 5a\mathbf{x} + 2a\mathbf{y} - 6a\mathbf{z}$$

$$\mathbf{r}_{AB} = \mathbf{r}_B - \mathbf{r}_A = 4a\mathbf{x} + 2a\mathbf{y} - 9a\mathbf{z}$$

- b. Due to the principle of charge conservation the time rate of decrease of charge within a given volume must be equal to the net outward current flow through the closed surface of the volume.

$$I_{\text{out}} = \oint \mathbf{J} \cdot d\mathbf{s} = - \frac{dQ}{dt}$$

By simplifying this

$$\boxed{\nabla \cdot \mathbf{J} = - \frac{\partial \rho}{\partial t}}$$

- c. Maxwell's equations

$$\begin{aligned} \nabla \cdot \mathbf{D} &= \rho & \nabla \times \mathbf{E} &= 0 & \nabla \times \mathbf{E} &= - \frac{\partial \mathbf{B}}{\partial t} \\ \nabla \cdot \mathbf{B} &= 0 & (\text{or}) \quad \nabla \times \mathbf{H} &= \mathbf{J} & \nabla \times \mathbf{H} &= \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \end{aligned}$$

- d. The no. of magnetic flux lines per unit area is called magnetic flux density.

$$B = \mu_0 H$$

e.

Conduction current density

$$J = \sigma E$$

It is due to the movement of free charges (like electrons) in a conductor

It exists in conductors

Displacement current density

$$J_d = \frac{\partial D}{\partial t}$$

It is introduced by Maxwell's for the time varying electric field region with no free charge flow.

It can exist in both conductor & insulation.

f.

Faraday's Law :- It states that The induced emf in any closed circuit is equal to the time rate of change of magnetic flux linkage by the circuit.

$$V_{emf} = -\frac{d\Phi}{dt} = -N \frac{d\psi}{dt}$$

g. Wave equation

$$\nabla^2 E_S - \gamma^2 E_S = 0$$

$$\nabla^2 H_S - \gamma^2 H_S = 0$$

h. Skin depth:- The skin depth is a measure of the depth to which an EM wave can penetrate the medium

$$\delta = \frac{1}{\alpha}$$

i

$$\Gamma = \frac{Z_L - Z_0}{Z_L + Z_0} = \frac{100 + j50 - 75}{100 + j50 + 75} = \frac{25 + j50}{175 + j50}$$

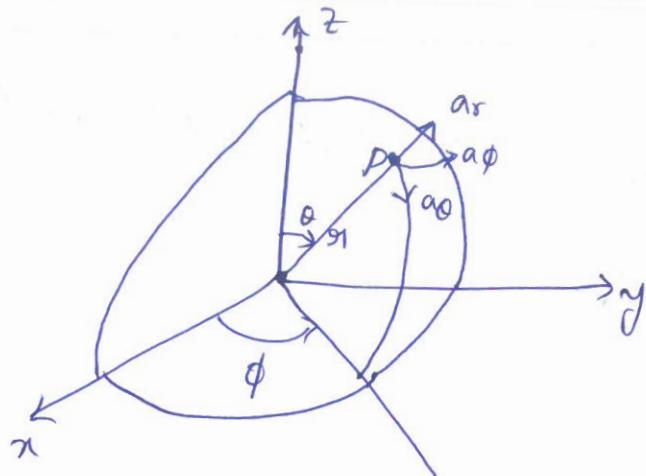
$$= 0.307 \angle 47.53^\circ$$

j

$$VSWR = \frac{|1 + \Gamma|}{|1 - \Gamma|}$$

Γ is the reflection coefficient

2 a Spherical co-ordinate system (SM)



point P and unit vectors in spherical co-ordinate System.

The spherical co-ordinates are (r, θ, ϕ) . Where r is defined as the distance from the origin to point P, θ is called as the angle b/w the z-axis and the position of vector of P, and ϕ is measured from the x-axis. The ranges of these variables are

$$0 \leq \theta < \infty$$

$$0 \leq \theta \leq \pi$$

$$0 \leq \phi \leq 2\pi$$

A vector in spherical co-ordinates may be represented as $\mathbf{A} = A_r \cdot \mathbf{a}_r + A_\theta \mathbf{a}_\theta + A_\phi \mathbf{a}_\phi$. Where A_r, A_θ and A_ϕ are called as components of the vector and $\mathbf{a}_r, \mathbf{a}_\theta, \mathbf{a}_\phi$ are called as unit vectors.

$$|\mathbf{A}| = \sqrt{A_r^2 + A_\theta^2 + A_\phi^2}$$

The unit vectors are mutually orthogonal. i.e

$$\mathbf{a}_r \cdot \mathbf{a}_r = \mathbf{a}_\theta \cdot \mathbf{a}_\theta = \mathbf{a}_\phi \cdot \mathbf{a}_\phi = 1$$

$$\mathbf{a}_r \cdot \mathbf{a}_\theta = \mathbf{a}_\theta \cdot \mathbf{a}_\phi = \mathbf{a}_\phi \cdot \mathbf{a}_r = 0$$

$$\mathbf{a}_r \times \mathbf{a}_\theta = \mathbf{a}_\phi$$

$$\mathbf{a}_\theta \times \mathbf{a}_\phi = \mathbf{a}_r$$

$$\mathbf{a}_\phi \times \mathbf{a}_r = \mathbf{a}_\theta$$

$$2.6 \quad \rho_L = 25 \text{nC/m} \quad (5M)$$

$$x = 3 \text{ m}$$

$$y = 4 \text{ m}$$

point (2, 3, 15)

The distance vector b/w point (2, 3, 15) and (3, 4, z) is

$$\vec{R} = -\hat{a}_x - \hat{a}_y$$

Since the line charge is along the z-axis, so there is no a_z component

$$\therefore R = \sqrt{1+1} = \sqrt{2}$$

$$\hat{a}_R = \frac{-\hat{a}_x - \hat{a}_y}{\sqrt{2}}$$

$$E = \frac{\rho_L}{2\pi\epsilon_0 R} \hat{a}_R = \frac{25 \times 10^{-9} (-\hat{a}_x - \hat{a}_y)}{2\pi \times 8.85 \times 10^{-12} \times \sqrt{2} \times \sqrt{2}} = \frac{25 \times 10^{-9} (-\hat{a}_x - \hat{a}_y)}{111.26 \times 10^{12}} \\ = 0.224 \times 10^3 (-\hat{a}_x - \hat{a}_y) \\ = 224 (-\hat{a}_x - \hat{a}_y) \text{ V/m}$$

3.a Gauss's Law (5M)

It states that the total electric flux ψ through any closed surface is equal to the total charge enclosed by the surface.

Thus $\psi_{tot} = Q_{enc}$

i.e. $\psi = \oint_S \vec{D} \cdot d\vec{s} = \text{total charge enclosed } Q = \int_V \rho_v dv$

$$\boxed{Q = \oint_S \vec{D} \cdot d\vec{s} = \int_V \rho_v dv}$$

By applying divergence theorem to the middle term

$$\oint_S \vec{D} \cdot d\vec{s} = \int_V \nabla \cdot D dv$$

Comparing the two volume integrals

$$\boxed{\therefore \nabla \cdot D = \rho_v}$$

This is the first Maxwell's equation.

Laplace's & Poisson's equations (5M)

from the gaum's Law

$$\nabla \cdot D = \nabla \cdot \epsilon E = \rho_v \quad \& \quad -\nabla \cdot E = -\rho_v$$

$$E = -\nabla V \quad \dots \quad (2)$$

Substitute equa (2) in (1)

$$\nabla \cdot \epsilon (-\nabla V) = \rho_v$$

for a homogeneous medium

$$\boxed{\nabla^2 V = -\frac{\rho_v}{\epsilon}}$$

This equation is known as Poisson's equation.

if $\rho_v = 0$ (charge free or source free region) is considered

$$\boxed{\nabla^2 V = 0} \rightarrow \text{This equation is}$$

known as Laplace's equation.

4. a) Ampere's Circuital Law (5M)

It states that the line integral of the tangential component of H around a closed path is the same as the net current I_{enc} enclosed by the path.

i.e

$$\oint_C \vec{H} \cdot d\vec{l} = I_{enc} \quad \dots \quad (1)$$

Ampere's Law is applied to determine H when the current distribution is symmetrical.

By applying Stoke's theorem to the LHS of the above equa

$$I_{enc} = \oint_C \vec{H} \cdot d\vec{l} = \int_S (\nabla \times \vec{H}) \cdot d\vec{s} \quad \dots \quad (2)$$

$$\text{But } \mathcal{I}_{\text{enc}} = \int_S \bar{J} \cdot d\bar{s} \quad \text{--- (3)}$$

Comparing The Surface integral (eqn 2&3) it give

$$\boxed{\nabla \times H = J}$$

This equation is known as Maxwell's third equation. Here $\nabla \times H = J \neq 0$ i.e. magneto static field is not conservative.

4b) $H = 50 \sin \phi \hat{a}_z \text{ mA/m}^2$ (5M)

Point $(2, 0, 0)$

$J = ?$

$$\nabla \times H = J$$

$$\nabla \times H = \frac{1}{\mu} \begin{vmatrix} \hat{a}_x & \hat{a}_y & \hat{a}_z \\ \partial/\partial x & \partial/\partial y & \partial/\partial z \\ 0 & 0 & 50 \sin \phi \end{vmatrix}$$

$$= \frac{1}{\mu} \left[\frac{\partial}{\partial y} (50 \sin \phi) - 0 \right]$$

$$= \frac{1}{\mu} 50 \cos \phi = \frac{1}{2} \cdot 50 \cdot \cos 0$$

$$= \boxed{25}$$

5a) $H = 2ax + 5ay + az \text{ Alm}$ (5M)

$$\mu_r = 4$$

$$B = \mu H$$

$$= \mu_0 \cdot \mu_r \cdot H$$

$$= 4\pi \times 10^{-7} \times 4 \times (2ax + 5ay + az)$$

$$= (100 \cdot 5 \vec{a_x} + 251 \cdot 3 \vec{a_y} + 50 \cdot 26 \vec{a_z}) \times 10^{-7} \text{ Tesla}$$

5b) Biot - Savart's Law and MFI due to line current (SM)

It states that magnetic field intensity dH produced at a point P by the differential current element Idl is proportional to the product Idl and the sine of the angle α between the element and the line joining P to the element and is inversely proportional to the square of the distance R between P and the element.

$$dH \propto \frac{Idl \sin \alpha}{R^2}$$

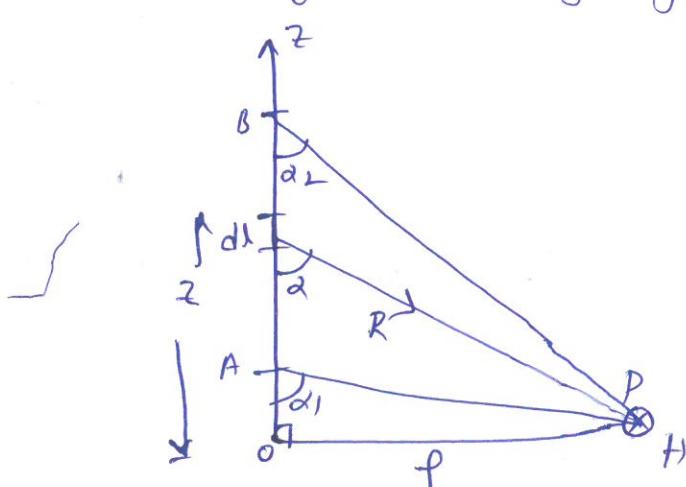
$$dH = \frac{K Idl \sin \alpha}{R^2}$$

In vector form

$$dH = \frac{Idl \times \vec{\alpha}}{4\pi R^2} = \frac{Idl \times \vec{R}}{4\pi R^3}$$

MFI due to line current

Assume a straight current carrying filamentary conductor of finite length AB along z -axis with its upper and lower ends respectively subtending angles α_2 and α_1 at point P .



field at point P due to a straight filamentary

If we consider the contribution dH at P due to an element dI at $(0, 0, z)$.

$$dH = \frac{Idl \times \vec{R}}{4\pi R^3}$$

But $dl = dz a_z$ and $\vec{R} = \varphi a_\varphi - z a_z$

$$\text{so } dl \times \vec{R} = \varphi dz a_\varphi a_\phi$$

Hence $H = \int_{-\infty}^{\infty} \frac{I \varphi dz}{[\varphi^2 + z^2]^{3/2}} a_\phi$

Let $z = \varphi \cot \alpha$, $dz = -\varphi \operatorname{cosec}^2 \alpha d\alpha$ Then

above equa becomes

$$H = -\frac{I}{4\pi} \int_{\alpha_1}^{\alpha_2} \frac{\varphi^2 \operatorname{cosec}^2 \alpha d\alpha}{\varphi^3 \operatorname{cosec}^3 \alpha} a_\phi$$

$$= -\frac{I a_\phi}{4\pi \varphi} \int_{\alpha_1}^{\alpha_2} \sin \alpha \cdot d\alpha$$

$$\therefore H = \frac{I}{4\pi \varphi} (\cos \alpha_2 - \cos \alpha_1) a_\phi$$

finite length

If conductor is of semi infinite length $\alpha_1 = 90^\circ$, $\alpha_2 = 0^\circ$

$$H = \frac{I}{4\pi \varphi} a_\phi$$

If conductor is of infinite length $\alpha_1 = 180^\circ$, $\alpha_2 = 0^\circ$

$$\therefore H = \frac{I}{2\pi \varphi} a_\phi$$

unit vector $\underline{ad} = \underline{dl} \times \underline{a_\varphi}$

6. Maxwell's equations differential and integral form (10M)

Differential form

$$\nabla \cdot D = \rho_v$$

$$\nabla \cdot B = 0$$

$$\nabla \times E = -\frac{\partial B}{\partial t}$$

$$\nabla \times H = J + \frac{\partial D}{\partial t}$$

Integral form

$$\oint \bar{D} \cdot d\bar{s} = \int_V \rho_v \cdot dv$$

$$\oint \bar{B} \cdot d\bar{s} = 0$$

$$\oint_C \bar{E} \cdot d\bar{l} = -\frac{\partial}{\partial t} \int_S \bar{B} \cdot d\bar{s}$$

$$\oint_L \bar{H} \cdot d\bar{l} = \int_S \left(J + \frac{\partial D}{\partial t} \right) \cdot d\bar{s}$$

Remarks

Gauss's Law

Non existence of magnetic charge
Faraday's Law

Ampere's Circu-
Law

from Gauss's Law total flux through a closed surface in $\Psi_{tot} = \oint \bar{D} \cdot d\bar{s} = Q_{enc}$ equals to the charge enclosed by S

$$\text{where } Q_{enc} = \int_V \rho_v \cdot dv$$

By applying divergence theorem to the term $\oint \bar{D} \cdot d\bar{s}$

$$\oint_S \bar{D} \cdot d\bar{s} = \int_V \nabla \cdot D \cdot dv$$

The volume integral

Comparing

$$\boxed{\nabla \cdot D = \rho_v} \quad \text{I equation}$$

Unlike electric flux lines, magnetic flux always close upon themselves. So it is no to have an isolated magnetic charge.

Thus The total flux through a closed surface must be zero i.e a magnetic field

$$\oint \vec{B} \cdot d\vec{s} = 0$$

By applying Divergence Theorem $\oint \vec{B} \cdot d\vec{s} = \int_V \nabla \cdot \vec{B} = 0$

$$\boxed{\therefore \nabla \cdot \vec{B} = 0} \quad - \text{II equation}$$

from Faraday's Law induced emf is equal to the rate of change of flux linkage

$$V_{emf} = -\frac{d\lambda}{dt} = -\frac{d\Psi}{dt} \quad (N=1)$$

from electric potential

$$\Psi = \int \vec{B} \cdot d\vec{s}$$

$$V_{emf} = \oint_C \vec{E} \cdot d\vec{l} = -\frac{d}{dt} \int_S \vec{B} \cdot d\vec{s}$$

Suppose we are considering stationary loop in a moving B field

$$V_{emf} = \oint_C \vec{E} \cdot d\vec{l} = -\int_S \frac{\partial \vec{B}}{\partial t}$$

By applying Stoke's theorem to the middle term

$$\oint_C \vec{E} \cdot d\vec{l} = \int_S \nabla \times \vec{E} d\vec{s} = -\int_S \frac{\partial \vec{B}}{\partial t}$$

$$\boxed{\therefore \nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}}$$

By removing surface integral
— III equation

from Ampere's Law

— ①

$$\nabla \times \vec{H} = \vec{J}$$

But the divergence of curl of any vector field is zero

$$\nabla \cdot (\nabla \times \vec{H}) = \nabla \cdot \vec{J} = 0 \quad - \text{②}$$

from Continuity of current equation

$$\nabla \cdot \vec{J} = -\frac{\partial \Psi}{\partial t} \neq 0 \quad - \text{③}$$

Equa 2 & 3 are incompatible. So modify equa ①

To agree with equa 2 & 3 add the term J_d

$$\nabla \times H = J + J_d$$

$$\nabla \cdot (\nabla \times H) = \nabla \cdot J + \nabla \cdot J_d = 0$$

$$\therefore \nabla \cdot J_d = -\nabla \cdot J$$

$$= \frac{\partial}{\partial t} \Phi_V \quad (\text{where } \nabla \cdot D = \Phi_V)$$

$$\nabla \cdot J_d = \frac{\partial}{\partial t} \nabla \cdot D$$

$$\boxed{\therefore J_d = \frac{\partial D}{\partial t}}$$

Substitute in equa ①

$$\boxed{\therefore \nabla \times H = J + J_d}$$

$$\text{Given } J_c = 0.02 \sin 10^9 t \text{ A/m}^2 \quad (5M)$$

$$\sigma = 10^3 \text{ mho/m}$$

$$\epsilon_r = 6.5$$

$$J_d = ?$$

$$J_d = \frac{\partial D}{\partial t}$$

$$J_c = \sigma E$$

$$0.02 \sin 10^9 t = 10^3 E$$

$$E = \frac{0.02 \sin 10^9 t}{10^3}$$

$$= 1.94 \times 10^{-4} \sin 10^9 t \text{ V/m}$$

$$D = \epsilon E = \epsilon_0 \cdot \epsilon_r \cdot E = 8.85 \times 10^{-12} \times 6.5 \times 1.94 \times 10^{-4} \sin 10^9 t$$
$$= 0.011 \sin 10^9 t \times 10^{-12} \text{ C/m}$$

$$J_d = \frac{\partial D}{\partial t} = \frac{\partial}{\partial t} (0.011 \sin 10^9 t \times 10^{-12})$$

$$= 0.011 \times 10^{-3} \times 10^9 \cos 10^9 t$$

$$= 0.011 \times 10^{-3} \cos 10^9 t \text{ A/m}^2$$

7b Inconsistency of Ampere's Law, Displacement current density (5M).

Consider the Ampere's Law for static fields

$$\nabla \times H = J \quad \text{--- (1)}$$

But the divergence of curl of any vector field is identically zero

$$\nabla \cdot (\nabla \times H) = 0 = \nabla \cdot J \quad \text{--- (2)}$$

Consider the continuity of current eqn

$$\nabla \cdot J = -\frac{\partial \Phi_V}{\partial t} \neq 0 \quad \text{--- (3)}$$

Equations 2 & 3 are incompatible. There is a inconsistency in ampere's Law i.e. eqn (1). To avoid this inconsistency add the term J_d to eqn (1)

$$\nabla \times H = J + J_d.$$

Apply divergence on both sides & vector identity

$$\nabla \cdot (\nabla \times H) = (\nabla \cdot J + \nabla \cdot J_d) = 0$$

$$\begin{aligned}\therefore \nabla \cdot J_d &= -\nabla \cdot J \\ &= -\left(-\frac{\partial \Phi_V}{\partial t}\right) \\ &= \frac{\partial}{\partial t}(\Phi_V)\end{aligned}$$

$$\nabla \cdot J_d = \frac{\partial}{\partial t}(\nabla \cdot D)$$

$$(\because \nabla \cdot D = \Phi_V)$$

Gauss' Law

$$\boxed{\therefore J_d = \frac{\partial D}{\partial t}}$$

\therefore Therefore displacement current density $J_d = \frac{\partial D}{\partial t}$ and displacement current is $J_d = \int_S J_d \cdot ds$. Therefore the Maxwell's eqn is modified as

$$\boxed{\nabla \times H = J + J_d}$$

8. Good Conductors and lossless Dielectrics, wave propagation in Good Conductors (10M)

For a lossless dielectric $\sigma = 0$ & $\alpha = 0$, $\epsilon = \epsilon_0 \epsilon_r$
 $\mu = \mu_0 \cdot \mu_r$ (or) $\sigma \ll \omega \epsilon_r$.

For Good Conductors the conductivity is very high compared to the wave frequency i.e $\sigma \gg \omega \epsilon_r$
 $\sigma \approx \infty$, $\epsilon = \epsilon_0$, $\mu = \mu_0 \cdot \mu_r$.

$$\gamma = \sqrt{j\omega\mu(\sigma + j\omega\epsilon)}$$

Since $\sigma \gg \omega \epsilon_r$, so we neglect the imaginary part

$$\gamma = \sqrt{j\omega\mu\sigma} = \sqrt{\omega\mu\sigma} \angle 45^\circ$$

$$\sqrt{\omega\mu\sigma} \left[\frac{1}{\sqrt{2}} + j \frac{1}{\sqrt{2}} \right] = \sqrt{\frac{\omega\mu\sigma}{2}} + j \sqrt{\frac{\omega\mu\sigma}{2}}$$

$$\therefore \alpha = \sqrt{\frac{\omega\mu\sigma}{2}}$$

$$\text{and } \beta = \sqrt{\frac{\omega\mu\sigma}{2}}$$

Thus for good conductors α and β are equal

In a highly conducting medium α is proportional to $\sqrt{\sigma}$, the losses are very high and the wave attenuates rapidly.

Intrinsic impedance η

$$\eta = \sqrt{\frac{\omega\mu}{\sigma + j\omega\epsilon}}$$

for a good conductor $\sigma \gg \omega \epsilon_r$

$$\gamma = \sqrt{\frac{j\omega\mu}{\sigma}}$$

$$\text{(or)} \quad \gamma = \sqrt{\frac{\omega\mu}{\sigma}} \quad \angle 45^\circ$$

phase velocity $v_p = \frac{\omega}{\beta} = \frac{\omega}{\sqrt{\frac{\omega\mu\sigma}{2}}}$

$$\therefore v_p = \sqrt{\frac{2\omega}{\mu\sigma}}$$

wave length $\lambda = \frac{2\pi}{\beta}$

so from the value of γ we observed

that E field leads H by 45° if

$$\vec{E} = E_0 e^{-\alpha z} \cos(\omega t - \beta z) \hat{ax}$$

$$\vec{H} = \frac{E_0}{\sqrt{\frac{\omega\mu}{\sigma}}} e^{-\alpha z} \cos(\omega t - \beta z - 45^\circ) \hat{ay}$$

\therefore E (or) H wave travels in a conducting medium its amplitude is attenuated by the factor $e^{-\alpha z}$. The distance through which the wave amplitude is decreased by a factor e (about 37%) is called skin depth or depth of penetration of the medium.

$$\text{i.e. } E_0 e^{-\alpha z} = E_0 \cdot e^{-1}$$

$$(2) \delta = \frac{1}{\alpha} \rightarrow \text{It is valid for any medium}$$

The skin depth is a measure of depth to which an EM wave can penetrate into the medium.

for good conductors $\delta = \frac{1}{\alpha} = \frac{1}{\sqrt{\pi f \mu \sigma}}$

9.a Poynting Theorem (SM)

Energy can be transported from one point to another point by mean of EM wave. The rate of change of such energy transportation can be obtained from Maxwell eqns.

$$\nabla \times E = -\frac{\partial B}{\partial t} \Rightarrow -\mu \cdot \frac{\partial H}{\partial t} - \textcircled{1}$$

$$\nabla \times H = J + \frac{\partial D}{\partial t} \Rightarrow \sigma E + \epsilon \frac{\partial E}{\partial t} - \textcircled{2}$$

Dotting both sides of eqn $\textcircled{2}$ with E gives

$$E \cdot (\nabla \times H) = \sigma E^2 + E \cdot \epsilon \frac{\partial E}{\partial t} - \textcircled{3}$$

Consider the vector identity

$$\nabla \cdot (A \times B) = B \cdot (\nabla \times A) - A \cdot (\nabla \times B)$$

Applying this vector identity to eqn $\textcircled{3}$ Let $A = H$ & $B = E$ given

$$H \cdot (\nabla \times E) + \nabla \cdot (H \times E) = \sigma E^2 + \epsilon E \frac{\partial E}{\partial t} - \textcircled{4}$$

$$= \sigma E^2 + \frac{1}{2} \epsilon \frac{\partial}{\partial t} E^2$$

Dotting both sides of eqn $\textcircled{1}$ with H gives

$$H \cdot (\nabla \times E) = -\mu H \frac{\partial H}{\partial t} = -\frac{1}{2} \mu \frac{\partial H^2}{\partial t} - \textcircled{5}$$

Substitute the $H \cdot (\nabla \times E)$ in eqn $\textcircled{4}$ given

$$\nabla \cdot (H \times E) - \frac{1}{2} \mu \frac{\partial H^2}{\partial t} = \sigma E^2 + \frac{1}{2} \epsilon \frac{\partial E^2}{\partial t}$$

$$\Rightarrow -\nabla \cdot (E \times H) = \sigma E^2 + \frac{1}{2} \epsilon \frac{\partial E^2}{\partial t} + \frac{1}{2} \mu \frac{\partial H^2}{\partial t}$$

$$\Rightarrow \nabla \cdot (E \times H) = -\sigma E^2 - \frac{1}{2} \epsilon \frac{\partial E^2}{\partial t} - \frac{1}{2} \mu \frac{\partial H^2}{\partial t}$$

Taking volume integral on both sides

$$\int_V \nabla \cdot (E \times H) dV = -\frac{\partial}{\partial t} \int_V \left[\frac{1}{2} \epsilon E^2 + \frac{1}{2} \mu H^2 \right] dV - \int_V \sigma E^2 dV$$

Apply divergence theorem to the LHS

$$\oint_S (E \times H) dS = -\frac{\partial}{\partial t} \int_V \left[\frac{1}{2} \epsilon E^2 + \frac{1}{2} \mu H^2 \right] dV - \int_V \sigma E^2 dV \quad \textcircled{6}$$

Poynting Theorem states that the net power flowing out of the given volume 'V' is equal to the time rate of decrease in the energy stored within V minus the conduction losses.

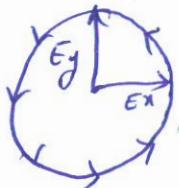
9b) Circular & Elliptical polarization (5M)

Consider a uniform plane wave travelling in the \hat{z} -direction. With the electric field components \vec{E}_x and \vec{E}_y not in phase, i.e. they reach their maximum values at different instants of time. Then the direction of the resultant electric vector \vec{E} will vary with time.

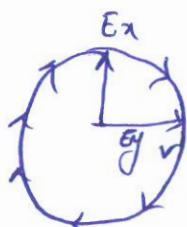
If \vec{E}_x and \vec{E}_y have equal magnitude with a 90° phase difference then the locus of the resultant vector \vec{E} is a circle. This wave is called a circularly polarized wave.

$E_x^2 + E_y^2 = E_a^2$. This equa represent the locus of a circle, E_a is the amplitude at $z=0$.

In circular polarization if \vec{E}_y leads \vec{E}_x by 90° then it is called a left hand circular polarization. If \vec{E}_y lags behind \vec{E}_x by 90° the direction of rotation in a right handed screw advancing in the \hat{z} -direction is called right hand circularly polarized wave.



LHC polarization



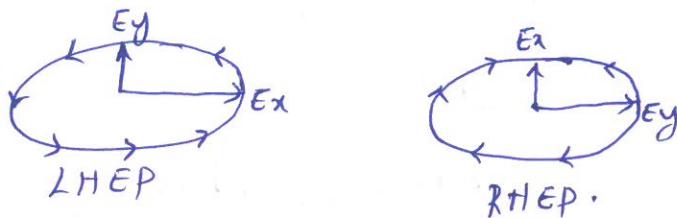
RHC polarization

Elliptical polarization

If \vec{E}_x and \vec{E}_y have different magnitudes with 90° phase difference then the locus of the resultant vector \vec{E} is an ellipse. The wave is called an elliptical polarized wave.

$$\frac{\vec{E}_x^2}{E_1^2} + \frac{\vec{E}_y^2}{E_2^2} = 1 \rightarrow \text{This equation represents the locus of an ellipse.}$$

If \vec{E}_y leads \vec{E}_x by 90° the direction of rotation in a left handed screw advancing in the $-z$ -direction is called left hand elliptically polarized wave. Similarly if \vec{E}_y lags \vec{E}_x by 90° , the direction of rotation in a right handed screw advancing in the $-z$ -direction then the wave is called a right hand elliptically polarized wave.



Input impedance of a transmission line (5M)

It is the impedance at the i/p (or) generator side of the line. It is represented as Z_{in} . Consider the voltage and current eqns of a transmission line at point z are

$$V(z) = V^+ e^{Rz} + V^- e^{-Rz}$$

$$I(z) = \frac{V^+}{Z_0} e^{Rz} + \frac{V^-}{Z_0} e^{-Rz}$$

Z_0 is the characteristic impedance.

The line impedance at point z is

$$Z(z) = \frac{V(z)}{I(z)} = Z_0 \frac{e^{\gamma z} + \Gamma_L e^{-\gamma z}}{e^{\gamma z} - \Gamma_L e^{-\gamma z}}$$

Let us assume $\Gamma_L = \frac{Z_L - Z_0}{Z_L + Z_0}$ and Γ_L

is the reflection coefficient at load. Substitute the value of Γ_L in the above equation

$$\begin{aligned} Z(z) &= Z_0 \frac{((Z_L + Z_0)e^{\gamma z} + (Z_L - Z_0)e^{-\gamma z})}{((Z_L + Z_0)e^{\gamma z} - (Z_L - Z_0)e^{-\gamma z})} \\ &= Z_0 \frac{Z_L(e^{\gamma z} + e^{-\gamma z}) + Z_0(e^{\gamma z} - e^{-\gamma z})}{Z_0(e^{\gamma z} + e^{-\gamma z}) + Z_L(e^{\gamma z} - e^{-\gamma z})} \end{aligned}$$

Substitute $\cosh \gamma z = \frac{e^{\gamma z} + e^{-\gamma z}}{2}$ and $\sinh \gamma z = \frac{e^{\gamma z} - e^{-\gamma z}}{2}$

in the above equation

$$Z(z) = Z_0 \frac{Z_L \cosh \gamma z + Z_0 \sinh \gamma z}{Z_0 \cosh \gamma z + Z_L \sinh \gamma z} = Z_0 \cdot \frac{Z_L + Z_0 \tanh \gamma z}{Z_0 + Z_L \tanh \gamma z}$$

Suppose if z is at s/p side $Z(z) = Z_{in}$

$$\therefore Z_{in} = Z_0 \cdot \frac{Z_L + Z_0 + \tanh \gamma z}{Z_0 + Z_L + \tanh \gamma z}$$

$$L = 26 \text{ H/m}$$

$$C = 2 \text{ PF/m}$$

$$G_I = 0$$

$$f = 5 \text{ MHz}$$

$$\omega = 2\pi f = 31.4 \times 10^6 \text{ rad/sec}$$

$$Z = R + j\omega L$$

$$= 25.23 + j 31.4 \times 10^6 \times 26 = 25.23 + 816400000 j$$

$$= 816400000 \angle 89.99^\circ$$

$$Y = G + j\omega C$$

$$= j 31.4 \times 10^6 \times 2 \times 10^{-12} = 6.28 \times 10^{-5} j$$

$$= 6.28 \times 10^{-5} \angle 90^\circ$$

$$r = \sqrt{Z \times Y}$$

$$= \sqrt{816400000 \angle 89.99^\circ \times 6.28 \times 10^{-5} \angle 90^\circ}$$

$$= \sqrt{51269.92 \angle 180^\circ}$$

$$= 226.4 \angle 90^\circ$$

$$0 + j226.4$$

$$d = 0; B = 226.4 \text{ rad/m}$$

11a

For a long line transmission line $R=0, G_I=0$. So the line is made of perfect conductor and perfect dielectric (5M) conditions for long transmission line

$$r = \sqrt{(R + j\omega L)(G_I + j\omega C)}$$

$$Z_0 = \sqrt{\frac{R + j\omega L}{G_I + j\omega C}}$$

By substituting $R=0, G_I=0$

$$d + jB = \sqrt{j\omega L \times j\omega C} = j\omega \sqrt{LC}$$

$$Z_0 = \sqrt{j\omega L / j\omega C} = \sqrt{4/c}$$

$$\therefore \alpha = 0; \beta = \omega \sqrt{Lc} \quad \& \quad Z_0 = \sqrt{4/c}$$

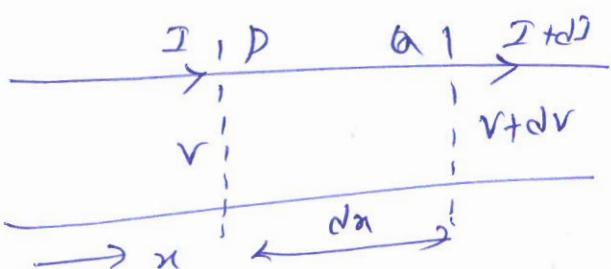
$$\text{Phase velocity } V_p = \omega / \beta = \frac{1}{\sqrt{Lc}} = \frac{1}{\sqrt{\mu \epsilon}}$$

11b Transmission line Equations (5M)

Consider a transmission line with two parallel conductors. Let R, L, G and C be the primary constants.

Assume that these values do not vary with frequency.
Consider a point P on the line at a distance x from the source as shown in fig.

Let another point A be at a small distance dx from point P .



Let V and I be the voltage and current at point P . Since the voltage and currents are uniformly distributed along the line, at point A let the voltage be $V + dV$ and the current be $I + dI$.

For a small length dx of the line the series impedance is $(R + j\omega L)dx$ and the shunt admittance is $(G + j\omega C)dx$.

The potential difference b/w P and A is

$$V - (V + dV) = I(R + j\omega L)dx$$

and The current difference b/w p and q is

$$I - (I + dI) = V(G_i + j\omega C)dx$$

$$\therefore -\frac{dV}{dx} = (R + j\omega L) \quad \& \quad -\frac{dI}{dx} = (G_i + j\omega C)V$$

Taking derivatives of above eqns in

$$-\frac{d^2V}{dx^2} = (R + j\omega L) \frac{dI}{dx}$$

Substitute the value of $\frac{dI}{dx}$

$$+\frac{d^2V}{dx^2} = (R + j\omega L)(G_i + j\omega C)V$$

Similarly $\frac{d^2I}{dx^2} = (R + j\omega L)(G_i + j\omega C)V$

$$\text{Let } \gamma^2 = (R + j\omega L)(G_i + j\omega C); \gamma = \alpha + j\beta$$

α in attenuation Constant & β in phase constant

$$\left[\therefore \frac{d^2V}{dx^2} = \gamma^2 V; \quad \frac{d^2I}{dx^2} = \gamma^2 I \right]$$

These are the differential eqns of the transmission lines. The standard solutions for these eqns are

$$V = ae^{\gamma x} + be^{-\gamma x}$$

$$\& I = ce^{\gamma x} + de^{-\gamma x}$$

where a, b, c, d are the constants

By Simplifying the above equations

$$V = a e^{\gamma x} + b e^{-\gamma x} \quad \&$$

$$I = \frac{1}{Z_0} (b e^{-\gamma x} - a e^{\gamma x})$$

Interna of hyperbolic

Substitute e^{rx} = $\cosh rx + \sinh rx$ &
 e^{-rx} = $\cosh rx - \sinh rx$ Then

$V = A \cosh rx + B \sinh rx$

$I = \frac{-1}{Z_0} (A \sinh rx + B \cosh rx)$