| Course Code | 20ME4702B | Year | IV | Semester | Ι |
|--------------------------------------|------------------------------|-------------------------------|------------|---------------|----------------------------------|
| Course Category | Professional Elective- IV | Branch | Mechanical | Course Type | Theory |
| Credits | 3 | L – T – P | 3-0-0 | Prerequisites | Basic electrical and electronics |
| Continuous Internal Evaluation | 30 | Semester End Evaluation | 70 | Total Marks | 100 |

MECHATRONICS

Course Outcomes: Upon successful completion of the course, the student will be able to

| | Statement | Skill | Level | Units |
|------------|--|------------------------------|-------|-----------|
| CO1 | Explain the concepts related to elements of Mechatronic systems. | Understand, Communication | L2 | 1,2,3,4,5 |
| CO2 | Summarize the construction and working of sensors used in building mechatronic systems. | Apply, Communication | L3 | 1 |
| CO3 | Illustrate various types of actuation systems and their components. | Apply, Communication | L3 | 2 |
| CO4 | Develop mathematical models using building blocks and make use of these models to find the dynamic response. | Apply, Communication | L3 | 3 |
| CO5 | Summarize the construction and working of closed loop controllers, Micro-processor and Micro controllers. | Apply, Communication | L3 | 4 |
| CO6 | Illustrate the features and applications of digital logic, PLC and of Fuzzy logic. | Apply, Communication | L3 | 5 |

| | Contribution of Course Outcomes towards achievement of Program Outcomes | | | | | | | | | | | | | |
|-----|---|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|
| | Strength of correlations (3: High, 2: Moderate, 1: Low) | | | | | | | | | | | | | |
| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 |
| CO1 | 3 | | | | | | | | | 2 | | 2 | 3 | 1 |
| CO2 | 3 | | | | | | | | | 2 | | 2 | 3 | 1 |
| CO3 | 3 | | 3 | | | | | | | 2 | | 2 | 3 | 1 |
| CO4 | 3 | 3 | | | 2 | | | | | 2 | | 2 | 3 | 1 |
| CO5 | 3 | | | | 2 | | | | | 2 | | 2 | 3 | 1 |
| CO6 | 3 | | | | 2 | | | | | 2 | | 2 | 3 | 1 |

| | Syllabus | | | | |
|------|--|----------------|--|--|--|
| UNIT | Course Content | Mapped CO s | | | |
| Ι | INTRODUCTION: Definition of Mechatronics, evolution of mechatronics, systems, measurement systems, control systems, mechatronic design process, traditional design and mechatronic design, applications of mechatronic systems, advantages and disadvantages of mechatronic systems. SENSORS: classification of sensors, basic working principles, Velocity sensors – Proximityand Range sensors, ultrasonic sensor, laser interferometer transducer, Hall Effect sensor, inductive proximity switch. Light sensors – Photodiodes, phototransistors, tactile sensors – PVDF tactile sensor, microswitch and reed switch, Piezoelectric sensors, vision sensor | CO1 CO2 | | | |

| II | PNEUMATIC AND HYDRAULIC ACTUATION SYSTEMS: Actuation systems, Pneumatic and Hydraulic systems- constructional details of filter, lubricator, regulator, direction control valves, pressure control valves, flow control valves, actuators-linear and rotary. ELECTRICAL ACTUATION SYSTEMS: Electrical systems, Mechanical switches, solid state switches, solenoids, DC motors, AC motors, stepper motors. Characteristics of pneumatic, hydraulic, electrical actuators and their limitations. | CO1 CO3 |
|-----|---|------------|
| III | BASIC SYSTEM MODELS: Mathematical models, mechanical system building blocks, electric system building blocks, fluid system building blocks, thermal system building blocks. DYNAMIC RESPONSES OF SYSTEMS: Transfer function, Modelling dynamic systems, first order and second order systems. | CO1 CO4 |
| IV | CLOSED LOOP CONTROLLERS: Classification of control systems, feedback, closed loop and open loop systems, continuous and discrete processes, control modes, two step mode, proportional mode, derivative control, integral control, PID controller. MICROPROCESSOR AND MICRO CONTROLLER: Introduction, Architecture of a microprocessor (8085), Architecture of a Micro controller, Difference betweenmicroprocessor and a micro controller. | CO1 CO5 |
| V | DIGITAL LOGIC: Digital logic, number systems, logic gates, Boolean algebra, Karnaugh maps, application of logic gates, sequential logic, transducer Signal Conditioning and devicesfor data conversion. PROGRAMMABLE LOGIC CONTROLLERS: Introduction, basic structure, input/output processing, programming, mnemonics, timers, internal relays and counters, shift register, master and jump controls. Data handling, Analog input/output, selection of a PLC. FUZZY LOGIC APPLICATIONS IN MECHATRONICS: Fuzzy logic systems, Fuzzy control, Uses of Fuzzy expert systems. | CO1 CO6 |

Learning Resources

- Text Books:
 1. Mechatronics Electronic Control Systems in Mechanical and Electrical Engineering, (3rdedition), by W Bolton, Pearson Education Press, 2005.
 - 2. Mechatronics System Design, 5th Indian reprint, 2009, by Devdas shetty, Richard A. kolk,PWS Publishing Company

Reference Books

- 1. Mechatronics Source Book, by Newton C Braga, Thomson Publications, Chennai.
- 2. Mechatronics, by N. Shanmugam, Anuradha Agencies Publishers.
- 3. Control sensors and actuators, by C.W.Desilva, Prentice Hall.
- 4. Design with Microprocessors for Mechanical Engineers, by Stiffler, A.K.McGraw- Hill(1992).

E-Resources & other digital Material

1. https://onlinecourses.nptel.ac.in/noc22_me54/course