## GEOMETRIC MODELLING

| Course Code | 22MEMD1T4 | Year | I | Semester | I |
| :--- | :---: | :--- | :---: | :--- | :---: |
| Course <br> Category | Programme Core | Branch | ME | Course Type | Theory |
| Credits | 4 | L-T-P | $4-0-0$ | Prerequisites | Nil |
| Continuous <br> Internal <br> Evaluation: | 40 | Semester <br> End <br> Evaluation: | 60 | Total Marks: | 100 |

Course outcomes: At the end of the course, the student will be able to:

| CO | Statement | BTL | Units |
| :---: | :--- | :---: | :---: |
| CO 1 | Express types of manipulation techniques, <br> mathematical representation schemes for <br> various entities used in geometric modeling. | L 3 | 1 |
| CO 2 | Formulate algebraic and geometric form of a cubic <br> spline, Bezier, and B-Spline curves and their <br> derivatives. | L 3 | 2 |
| CO 3 | Develop parametric representation of analytic and <br> synthetic surfaces. | L 3 | 3 |
| CO 4 | Distinguish various schemes used for construction <br> of solid models. | L 3 | 4 |

Contribution of Course outcomes towards achievement of programme outcomes $\boldsymbol{\&}$
Strength of correlations (High:3, Medium: 2, Low:1)

|  | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CO 1 | 2 | 2 | 3 |  | 3 | 2 |  | 1 | 1 |  |  | 2 | 3 | 2 |
| CO 2 | 2 | 2 | 3 |  | 3 | 2 |  | 1 | 1 |  |  | 2 | 3 | 2 |
| CO 3 | 2 | 2 | 3 |  | 3 | 2 |  | 1 | 1 |  |  | 2 | 3 | 2 |
| CO 4 | 2 | 2 | 3 |  | 3 | 2 |  | 1 | 1 |  |  | 2 | 3 | 2 |


| Syllabus |  |  |  | Contents | Mapped <br> CO |
| :---: | :--- | :---: | :---: | :---: | :---: |
| Unit | TRANSFORMATIONS IN GEOMETRIC MODELING: Introduction, <br> Translation, Scaling, Reflection, Rotation in 2D and 3D. Homogeneous |  |  |  |  |
| I | representation of transformation, Concatenation of transformations. <br> CUBIC SPLINES: Definition, Explicit and implicit equations, parametric <br> equations. Algebraic and geometric form of cubic spline, tangent vectors, <br> parametric space of a curve, blending functions, four-point form, <br> reparametrization, truncating and subdividing of curves. | CO1 |  |  |  |


|  | BEZIER CURVES: Bezier curve definition, matrix representation of Bezier <br> curves, Bernstein basis, equations of Bezier curves, properties, derivatives, <br> increasing the flexibility of Bezier curves, degree elevation. <br> B-SPLINE CURVES: B-Spline curve definition, properties, convex hull <br> properties of Bspline, knot vector, B-spline basis function, B-spline curve <br> control, open, periodic, non-uniform B-spline curves, matrix formulation of B- <br> spline curve, end conditions of periodic Bspline curve, equations, and <br> derivatives. | CO2 |
| :---: | :--- | :---: |
| III | INTRODUCTION: Surface Models, Surface Representation. Parametric <br> Representation of Analytic Surfaces - Plane Surface, Ruled Surface, Surface <br> of Revolution, Tabulated Cylinder. <br> Parametric Representation of Synthetic Surfaces - Hermit Bi-cubic Surface, <br> Bezier Surface, B-Spline Surface, Coons Surface, Gaussian curvature. | CO3 |
|  | SOLIIDS IN GEOMETRIC MODELING FOR DESIGN: Solid entities, <br> Boolean operations, Topological aspects, Invariants. B-rep of Solid <br> Modelling, CSG approach of solid modelling. Popular modeling methods in <br> CAD. | CO4 |

## Learning Resources

Text Book(s):

1. Geometric Modeling (1st edition) by Micheal. E. Mortenson, McGraw Hill Publishers, First edition
2. Elements of Computer Graphics (1st edition) by Roger \& Adams Tata McGraw Hill. First edition

## References:

1. An Introduction to Nurbs with Historical perspective (1st edition) by David F Rogers. First edition
