

**MECHATRONICS**

<b>Course Code</b>	20ME2702A	<b>Year</b>	IV	<b>Semester</b>	I
<b>Course Category</b>	Open Elective-IV	<b>Branch</b>	ME	<b>Course Type</b>	Theory
<b>Credits</b>	3	<b>L – T – P</b>	3 – 0 – 0	<b>Prerequisites</b>	BEE
<b>Continuous Internal Evaluation</b>	30	<b>Semester End Evaluation</b>	70	<b>Total Marks</b>	100

**Course Outcomes:** Upon successful completion of the course, the student will be able to

	<b>Statement</b>	<b>Skill</b>	<b>BTL</b>	<b>Units</b>
<b>CO1</b>	Explain the concepts related to elements of Mechatronic systems.	Understand, Communication	L2	1,2,3,4,5
<b>CO2</b>	Summarize the construction and working of sensors used in building mechatronics systems.	Apply, Communication	L3	1
<b>CO3</b>	Illustrate various types of actuation systems and their components.	Apply, Communication	L3	2
<b>CO4</b>	Develop mathematical models using building blocks and make use of these models to find the dynamic response.	Apply, Communication	L3	3
<b>CO5</b>	Summarize the construction and working of closed loop controllers, Micro processor and Micro controllers.	Apply, Communication	L3	4
<b>CO6</b>	Illustrate the features and applications of digital logic, PLC and of Fuzzy logic.	Apply, Communication	L3	5

**Contribution of Course outcomes towards achievement of Program outcomes  
& Strength of correlations (High:3, Medium: 2, Low:1)**

	<b>PO1</b>	<b>PO2</b>	<b>PO3</b>	<b>PO4</b>	<b>PO5</b>	<b>PO6</b>	<b>PO7</b>	<b>PO8</b>	<b>PO9</b>	<b>PO10</b>	<b>PO11</b>	<b>PO12</b>	<b>PSO1</b>	<b>PSO2</b>
<b>CO1</b>	3									2		2	3	1
<b>CO2</b>	3									2		2	3	1
<b>CO3</b>	3		3							2		2	3	1
<b>CO4</b>	3	3			2					2		2	3	1
<b>CO5</b>	3				2					2		2	3	1
<b>CO6</b>	3				2					2		2	3	1

<b>Syllabus</b>		
<b>UNIT</b>	<b>Contents</b>	<b>Mapped CO</b>
<b>I</b>	<p><b>INTRODUCTION:</b> Definition of Mechatronics, evolution of mechatronics, systems, measurement systems, control systems, mechatronic design process, traditional design and mechatronic design, applications of mechatronic systems, advantages and disadvantages of mechatronic systems.</p> <p><b>SENSORS:</b> classification of sensors, basic working principles, Velocity sensors – Proximity and Range sensors, ultrasonic sensor, laser interferometer transducer, Hall Effect sensor, inductive proximity switch. Light sensors – Photodiodes, phototransistors, tactile sensors – PVDF tactile sensor, micro-switch and reed switch, Piezoelectric sensors, vision sensor</p>	<b>CO1 CO2</b>

II	<b>PNEUMATIC AND HYDRAULIC ACTUATION SYSTEMS:</b> Actuation systems, Pneumatic and Hydraulic systems- constructional details of filter, lubricator, regulator, direction control valves, pressure control valves, flow control valves, actuators-linear and rotary. <b>ELECTRICAL ACTUATION SYSTEMS:</b> Electrical systems, Mechanical switches, solid state switches, solenoids, DC motors, AC motors, stepper motors. Characteristics of pneumatic, hydraulic, electrical actuators and their limitations.	CO1 CO3
III	<b>BASIC SYSTEM MODELS:</b> Mathematical models, mechanical system building blocks, electric system building blocks, fluid system building blocks, thermal system building blocks. <b>DYNAMIC RESPONSES OF SYSTEMS:</b> Transfer function, Modelling dynamic systems, first order and second order systems.	CO1 CO4
IV	<b>CLOSED LOOP CONTROLLERS:</b> Classification of control systems, feedback, closed loop and open loop systems, continuous and discrete processes, control modes, two step mode, proportional mode, derivative control, integral control, PID controller. <b>MICROPROCESSOR AND MICRO CONTROLLER:</b> Introduction, Architecture of a microprocessor (8085), Architecture of a Micro controller, Difference between microprocessor and a micro controller.	CO1 CO5
V	<b>DIGITAL LOGIC:</b> Digital logic, number systems, logic gates, Boolean algebra, Karnaugh maps, application of logic gates, sequential logic, transducer Signal Conditioning and devices for data conversion. <b>PROGRAMMABLE LOGIC CONTROLLERS:</b> Introduction, basic structure, input/output processing, programming, mnemonics, timers, internal relays and counters, shift register, master and jump controls. Data handling, Analog input/output, selection of a PLC. <b>FUZZY LOGIC APPLICATIONS IN MECHATRONICS:</b> Fuzzy logic systems, Fuzzy control, Uses of Fuzzy expert systems.	CO1 CO6

### Learning Resource

#### Text books:

1. Mechatronics Electronic Control Systems in Mechanical and Electrical Engineering, (3rd edition), by W Bolton, Pearson Education Press, 2005.
2. Mechatronics System Design, 5<sup>th</sup> Indian reprint, 2009, by Devdas shetty, Richard A. kolk, PWS Publishing Company

#### Reference books

1. Mechatronics Source Book, by Newton C Braga, Thomson Publications, Chennai.
2. Mechatronics, by N. Shanmugam, Anuradha Agencies Publishers.
3. Control sensors and actuators, by C.W.Desilva, Prentice Hall.
4. Design with Microprocessors for Mechanical Engineers, by Stiffler, A.K.McGraw- Hill(1992).

#### E-Resources & other digital Material:

1. [https://onlinecourses.nptel.ac.in/noc22\\_me54/course](https://onlinecourses.nptel.ac.in/noc22_me54/course)