

19EC3503 - Control Systems Engineering

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|--|--------------|---------------------------------|-------|----------------------|--------|
| Course Code | 19EC3503 | Year | III | Semester | I |
| Course Category | Program Core | Branch | ECE | Course Type | Theory |
| Credits | 3 | L-T-P | 3-0-0 | Prerequisites | Nil |
| Continuous Internal Evaluation: | 30 | Semester End Evaluation: | 70 | Total Marks: | 100 |

| Course Outcomes | |
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| Upon successful completion of the course, the student will be able to | |
| CO1 | Classify control systems and represent in various models (L2) |
| CO2 | Apply standard test signals to a system to determine their characteristics (L3) |
| CO3 | Make use of stability concepts to obtain the desired characteristics (L3) |
| CO4 | Determine the characteristics of a linear control system using various time and frequency domain tools (L5) |
| CO5 | Examine the system behaviour using various stability analysis techniques (L4) |

| Mapping of course outcomes with Program outcomes (CO/ PO/PSO Matrix) | | | | | | | | | | | | | | |
|---|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|
| Note: 1- Weak correlation 2-Medium correlation 3-Strong correlation | | | | | | | | | | | | | | |
| * - Average value indicates course correlation strength with mapped PO | | | | | | | | | | | | | | |
| COs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 |
| CO1 | 3 | 3 | 2 | 3 | 2 | | | 1 | 1 | 1 | | 1 | 2 | 1 |
| CO2 | 2 | 3 | 2 | 2 | 3 | | | 2 | 3 | 1 | | 2 | 2 | 1 |
| CO3 | 3 | 2 | 3 | 3 | 2 | | | 1 | 1 | 2 | | 1 | 3 | 2 |
| CO4 | 2 | 3 | 2 | 2 | 3 | | | 2 | 2 | 1 | | 1 | 2 | 2 |
| CO5 | 3 | 3 | 3 | 2 | 2 | | | 1 | 1 | 2 | | 1 | 2 | 1 |
| Average* (Rounded to nearest integer) | 3 | 3 | 2 | 2 | 2 | | | 1 | 2 | 1 | | 1 | 2 | 1 |

| Syllabus | | |
|-----------------|---|-----------|
| Unit No. | Contents | Mapped CO |
| I | Introduction: Concepts of control systems. Examples of control systems, classification of control systems, Block diagram algebra, Representation by Signal flow graph. Reduction using Mason's gain formula. Feedback Characteristics, Effects of feedback. Mathematical modelling of systems – Electrical, mechanical translational and rotational systems. | CO1 |
| II | Time Domain Analysis: Standard test signals, Time response of first and second order systems with standard input signals, Time domain specifications, steady state error and error constants. Effects of P, PI, PD and PID Controllers. | CO2, CO3 |

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| III | Stability Analysis in S-Domain: Concept of stability, Routh Hurwitz criterion. Construction of Root locus. Effects of adding poles and zeros to open loop transfer function on the root loci. | CO3,CO4,CO5 |
| IV | Frequency Response Analysis: Correlation between time and frequency responses. Determination of frequency domain specifications, Gain margin and Phase margin -Stability Analysis from Bode Plots, Polar plots and Nyquist plots. | CO3CO4,CO5 |
| V | State variable analysis: State, State variables, State variable representation, State variable form from Transfer function (Diagonal form), transfer function from State variable form, State transition matrix, properties of state transition matrix, Controllability and Observability | CO1 |

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| Learning Resources |
| Text Books |
| 1. M.Gopal, "Control Systems Engineering" , 3/e , Wiley Eastern Ltd., TMH ,2008 2. Benjamin C.Kuo, "Automatic Control Systems" ,7/e , Prentice Hall of India, 1997. |
| Reference Books |
| 1. Ogata, "Modern Control Engineering" , 2/e, Prentice Hall of India.,2011 2. R.C. Sukla, "Control Systems", 3/e, Dhanpatrai and Sons,1998 3. Control Systems Engg. , Nise– John wiley , 3rd Edition 2000 |
| e- Resources & other digital material |
| 1. https://www.udemy.com/topic/control-systems/ 2. https://ebooks.schandpublishing.com/detail/principles-control-system/9788121917780 3. https://library.villanova.edu/Find/Record/1437935/TOC |